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New Control Charts for a Multivariate Gamma Distribution

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Abstract

In this study, we introduce a multivariate gamma distribution, then, by defining a new statistic, three control charts called the MG charts, are proposed for this distribution. The first control chart is based on the exact distribution of this statistic, the second control chart is based on the Satterthwaite approximation, and the last is based on the normal approximation. The efficiency of the proposed control charts is evaluated by the average run length (ARL) criterion. The results show that whenever the magnitude of the parameter shifts c<1, the control chart based on the exact distribution has smaller ARL1s, while for c>1, the control chart based on Satterthwaite approximation show smaller values of ARL1s. Besides, the results show that for large changes (c>2.5), all proposed charts almost have equal ARL1s; i.e. they have the same performance.

Key Words: Multivariate gamma distribution; Chi-square distribution; Average run length; Satterthwaite approximation; Normal approximation.

1. Introduction

Control charts play an important role in statistical quality control to monitoring and improving a production process. Sometimes researchers are interested in the investigation of more than one quality characteristic simultaneously during the production. In this case, the process is called a multivariate process.

There are many works performed in the literature in the field of control charts for multivariate attribute processes. For more discussion, one may refer to; Aslam, et.al. (2017), Ali Raza and Aslam (2018), Cozzucoli and Marozzi (2018), Chiu and Kuo (2007). Similarly, many researchers worked on various control charts in which the correlated quality characteristics are of variable type and follow some continuous probability distributions. To the best of the authors' knowledge, there is no work on the use of the multivariate gamma distribution. Nonetheless, the univariate gamma distribution has been widely used in a variety of fields; Aksoy (2000), Agarwal and Kalla (1996), Mori, et.al. (2015), Tan, et.al. (2017), to design some control charts, see for example; Aslam, et.al. (2016), Derya and Canan (2012), Khan, et.al. (2017), Zhang, et.al. (2007).

In this paper, a structure of multivariate gamma (MG) distribution will be defined. Then, by definition of a new statistic and calculating its exact distribution, a control chart for an important quality parameter of this distribution will be proposed in Section 2. In Section 3, the efficiency of this control chart will be investigated. In Section 4, the following two approximations are used to obtain the control limits:

Case 1: Satterthwaite approximation (Casella and Berger (2002));

Case 2: The Wilson-Hilferty (WH) approximation (Wilson and Hilferty (1931)).

The efficiency of the above charts in terms of the average run length (ARL) is evaluated in Section 5. ARL is the expected number of samples (subgroups) taken before there is a signal (Montgomery (2013)). Finally, some conclusions are brought in Section 6.

2. Structure of a multivariate gamma control chart based on the exact distribution

Let Y_i , j = 1, 2, ..., p be random variables following a gamma distribution with the shape parameter $\alpha_i - \alpha_0$ and the scale parameter β . Suppose Y_0 is a random variable that follows a gamma distribution with the shape parameter α_0 and the scale parameter β . Assume that $Y_0, Y_1, ..., Y_p$ are mutually independent. Define $X_j = Y_j + Y_0, j = 1, 2, ..., p$.

Then, $X = (X_1, X_2, ..., X_n)$ follows a jointly p-variable gamma distribution. Each X_i follows a gamma distribution marginally with the shape parameter α_i and the scale parameter β , where the covariance between two variables (X_i, X_j) is equal to $\alpha_0 \beta^2$. By the above definition, the multivariate gamma model is constructed with positive correlation and equal covariance between variables. The probability density function (pdf) of this multivariate gamma distribution can be written as follows:

$$f_{(X_1,\dots,X_p)}(x_1,\dots,x_p) = \frac{1}{\Gamma(\alpha_0)\prod_{i=1}^p \Gamma(\alpha_i-\alpha_0)\beta^{(\sum_{i=1}^p \alpha_i)+\alpha_0(1-p)}} \int_0^{\min(x_1,\dots,x_p)} e^{-\frac{\sum_{i=1}^p x_i+x_0(1-p)}{\beta}} x_0^{\alpha_0-1} \prod_{i=1}^p (x_i - x_0)^{\alpha_i-\alpha_0-1} dx_0, \quad x_i > 0, \, \alpha_i > \alpha_0.$$
 (1)

The multivariate gamma distribution structure can be described with bellow example:

Suppose that a system has p independent components so that Y_i , is longevity i-th item, and has a gamma distribution with the shape parameter $\alpha_i - \alpha_0$ and the scale parameter β . When i-th item fails, it is repaired or replaced by another item. Assume that Y_0 is the time of repaired or replaced of i-th item, and has a gamma distribution with the shape parameter α_0 and the scale parameter β . In this case $X_i = Y_i + Y_0$ denotes the restart time of i-th item. Define the statistic *D* as follows:

$$D = \sum_{i=1}^{p} X_i. \tag{2}$$

The probability density function of *D* is given by

$$f_D(d) = \frac{e^{-d/p\beta} d^{\alpha_0 + \alpha^* - 1}}{p^{\alpha_0} \beta^{\alpha_0 + \alpha^*} \Gamma(\alpha_0 + \alpha^*)} F_{l,l}(\alpha^*, \alpha_0 + \alpha^*, \frac{d(1-p)}{p\beta}),$$
(3)

where, $\alpha^* = (\sum_{i=1}^p \alpha_i) - p\alpha_0$ and $F_{1,1}(a,b,z)$ denotes the hypergeometric function defined by

$$F_{1,1}(a,b,z) = \frac{\Gamma(b)}{\Gamma(a)\Gamma(b-a)} \int_0^1 t^{a-1} (1-t)^{b-a-1} \exp(tz) dt. \tag{4}$$

The probability density function of D given in Equation (3) is derived based on the method of variable transformation in the Appendix.

Fixing Type-I error at α , the lower and the upper control limits (LCL and UCL, respectively) are determined by solving the following two equations:

$$P(D < LCL) = \int_0^{LCL} f_D(t) dt = \frac{\alpha}{2},$$

$$P(D > UCL) = \int_{UCL}^{\infty} f_D(t) dt = \frac{\alpha}{2},$$
(5)

$$P(D > UCL) = \int_{UCL}^{\infty} f_D(t) dt = \frac{\alpha}{2}, \tag{6}$$

Under this control chart, the out-of-control probability (P_{out}^0) based on a single sample when the process is in-control is given by:

$$P(D \le LCL|\alpha_i = \alpha_{i0}) + P(D \ge UCL|\alpha_i = \alpha_{i0}). \tag{7}$$

The in-control ARL denoted by ARL₀ is the expected number of subgroups to be examined until the process is declared to be out-of-control when the process is truly in control. It is given by:

$$ARL_0 = \frac{1}{P_{out}^0} \,. \tag{8}$$

Now, suppose those shape parameters are changed from α_{i0} to $\alpha_{i1} = c\alpha_{i0}, i = 1, 2, ..., p$ for a constant c. Then, the probability of the process being declared out-of-control based on the single sample when the process is changed is given by:

$$P_{out}^1 = P(D \le LCL | \alpha_i = \alpha_{i1}) + P(D \ge UCL | \alpha_i = \alpha_{i1}). \tag{9}$$

Note that, the control limits are calculated when the process is in-control. The out-of-control ARL (ARL_1) for the changing process is given as:

$$ARL_1 = \frac{1}{p_{out}^1} \,. \tag{10}$$

3- The efficiency evaluation of the chart

In this section, the efficiency of the proposed control chart is evaluated using the ARL criterion. There are two types of ARL namely the in control (ARL_0) and the out-of-control (ARL_1) ARLs. The larger the value of the in-control and the smaller the value of the out-of-control ARL the better the performances of the chart are. Here, the ARL_1 s of the chart are examined for a 3-variable and a 2-variable process when ARL_0 s are fixed at 200 and 370 for each case. The results based on various parameter changes are shown in Tables 1 and 2, respectively. These results are obtained using MATLAB software.

Table 1. The ARL₁ of the MG control chart based on the exact distribution of D statistic, when p = 3 and $\beta = 4$.

	$\alpha = (3,3,3)$ ar	$ad \alpha_0 = 2$	$\alpha = (9,7,9)$	and $\alpha_0 = 2$	$\alpha = (5,1,3)$	and $\alpha_0 = 0.5$	$\alpha = (2,1,2)$	and $\alpha_0 = 0.5$
c	$ARL_0 = 370 \{ LCL = 4.99 UCL = 120.8 $	$ARL_0 = 200$ $\{LCL = 5.80$ UCL = 112.8	$ARL_0 = 370$ $\{LCL = 44.50$ UCL = 195.57	$ ARL_0 = 200 \{ LCL = 47.5 UCL = 188.72 $	$ARL_0 = 370 \{ LCL = 8.90 UCL = 99.1 $	$ARL_0 = 200$ $\{LCL = 9.9$ UCL = 92.82	$ARL_0 = 370$ $\{LCL = 2.10$ UCL = 78.34	$ ARL_0 = 200 {LCL = 2.50 UCL = 71.75} $
0.7	20.28	15.13	10.34	7.38	27.26	18.58	38.52	26.25
0.8	56.28	37.45	33.38	21.04	71.65	44.68	92.70	57.85
0.9	163.76	96.56	132.28	73.37	187.63	107.19	209.66	120.15
1	370.27	200.28	370.1	200	370.2	200.03	370.24	200.18
1.1	457.16	246.91	283.63	171.06	407.41	220.36	446.93	238.30
1.2	384.77	208.95	132.89	83.56	303.63	166.00	410.85	219.98
1.3	283.17	157.94	62.02	40.04	202.22	110.93	338.54	181.54
1.5	144.03	86.85	15.91	10.97	86.16	47.76	212.90	113.44
1.7	84.50	48.40	5.40	4.05	37.88	21.64	131.24	69.45
2.0	35.75	21.09	1.88	1.61	12.66	7.80	63.15	33.48
2.2	20.84	12.62	1.30	1.20	6.88	4.53	39.09	20.99
2.5	9.91	6.33	1.04	1.03	3.33	2.43	19.71	10.99
2.7	6.40	4.24	1.01	1.00	2.31	1.80	12.92	7.46
3.0	3.61	2.60	1.00	1.00	1.57	1.34	7.31	4.50
3.2	2.65	1.92	1.00	1.00	1.32	1.19	5.24	3.38
3.5	1.83	1.50	1.00	1.00	1.13	1.07	3.41	2.37
3.7	1.52	1.03	1.00	1.00	1.07	1.03	2.69	1.95

Table 2. The ARL₁ of the MG control chart based on the exact distribution of D statistic, when p = 2 and $\beta = 4$.

	$\alpha = (3,3)$ and $\alpha_0 = 2$		$\alpha = (2,2) \text{ and } \alpha_0 = 0.5$		$\alpha = (5,4)$ a	and $\alpha_0 = 2$	$\alpha = (2,6) \text{ and } \alpha_0 = 0.5$	
c	$ARL_0 = 370 \begin{cases} LCL = 2.60 \\ UCL = 81.16 \end{cases}$		$ARL_0 = 370 { LCL = 1.50 UCL = 59.59 }$	$ARL_0 = 200$ $\{LCL = 1.75$ UCL = 54.21	$ARL_0 = 370 \begin{cases} LCL = 7.80 \\ UCL = 96.84 \end{cases}$	$ \text{ARL}_0 = 200 \\ \text{LCL} = 8.80 \\ \text{UCL} = 91.62 $	$ARL_0 = 370$ $\{LCL = 7.60$ UCL = 81.36	$ARL_0 = 200 \begin{cases} LCL = 8.50 \\ UCL = 77.05 \end{cases}$
0.7	26.63	19.68	44.64	32.17	27.57	18.91	32.98	22.03
0.8	80.05	51.26	99.81	66.7	73.08	45.54	84.79	52.02
0.9	198.78	114.98	212.64	128.98	193.85	109.92	212.17	119.77
1	370.12	200.03	370	200.03	370.05	200.06	370.18	200.01
1.1	415.78	224.11	448.71	222.12	367.09	204.01	331.52	183.44
1.2	336.74	184.99	399.06	190.73	250.46	143.77	207.34	118.57
1.3	247.1	137.64	307.95	146.32	158.03	92.56	121.89	71.54
1.5	128.99	73.32	167.23	80.43	64.30	39.05	45.08	27.87
1.7	96.01	40.13	91.47	45.07	28.42	18.01	19.17	12.54
2.0	28.99	17.61	39.64	20.57	10.03	6.85	6.89	4.93
2.2	17.19	10.81	23.98	12.97	5.69	4.11	4.08	3.09
2.5	8.59	5.74	12.3	7.13	2.93	2.29	2.28	1.84
2.7	5.77	4.02	8.35	5.07	2.10	1.74	1.73	1.49
3.0	3.49	2.59	5.06	3.31	1.49	1.31	1.31	1.21

3.2	2.65	2.06	3.82	2.62	1.28	1.17	1.18	1.11
3.5	1.91	1.57	2.68	1.97	1.11	1.06	1.07	1.04
3.7	1.61	1.38	2.2	1.69	1.06	1.03	1.03	1.01

The conclusions made based on the results in Tables 1 and 2 are summarized as follow:

- 1- It is observed that for c > 1, when c increases, the ARL₁ decreases for all cases.
- 2- ARL₁ decreases rapidly when c > 2.
- 3- Most of the results show that if c > 1, small changes of c may not be detected (ARL₁ > ARL₀).

4. Structure of the multivariate gamma control chart based on approximation

In this section, two approximations are employed to obtain the control limits; the Satterthwaite approximation (Casella and Berger (2002)) and the Wilson-Hilferty (WH) approximation (Wilson and Hilferty (1931)).

Case1: Satterthwaite approximation

The Satterthwaite approximation is a suitable approach widely used today (Casella and Berger (2002)). Assume that the statistic D in Equation (2) approximately follows a gamma distribution with the shape parameter a and the scale parameter b. In the other words:

$$D \sim \Gamma(a,b)$$
. (11)

So, we have

$$E(D) = ab, (12)$$

and

$$Var(D) = ab^2. (13)$$

Using the method of moment estimation (MME) and the Satterthwaite approximation,

$$E(D) = E\left(\sum_{i=1}^{p} X_i\right) = ab,\tag{14}$$

$$E(D) = E(\sum_{j=1}^{p} X_j) = ab,$$

$$Var(D) = Var(\sum_{j=1}^{p} X_j) = ab^2.$$
(14)

Thus, we have

$$\sum_{j=1}^{p} E(X_j) = ab, \tag{16}$$

and

$$\sum_{j=1}^{p} Var(X_j) + 2\sum_{i < j} Cov(X_i, X_j) = ab^2.$$

$$(17)$$

Hence, from (16) and (17) it can be concluded that

$$a = \frac{\left(\sum_{i=1}^{p} \alpha_i\right)^2}{\sum_{i=1}^{p} \alpha_i + p(p-1)\alpha_0},$$
(18)

and

$$b = \beta \left[1 + \frac{p(p-1)\alpha_0}{\sum_{i=1}^p \alpha_i} \right]. \tag{19}$$

In the following, we assume use with 2a degrees of freedom. In other words $\frac{2D}{b} \approx \chi_{2a}^2 \; .$ In the following, we assume that b is known. From (11) it can be concluded that $\frac{2D}{h}$ has a chi-squared distribution

$$\frac{2D}{h} \approx \chi_{2a}^2 \ . \tag{20}$$

Thus, the control limits of the chart with the probability of Type-I error α can be obtained as:

$$P(D \ge UCL) = P\left(\frac{2D}{b} \ge \frac{2UCL}{b}\right) = P\left(\chi_{2a}^2 \ge \frac{2UCL}{b}\right) \le \alpha/2,$$

$$P(D \le LCL) = P\left(\frac{2D}{b} \le \frac{2LCL}{b}\right) = P\left(\chi_{2a}^2 \le \frac{2LCL}{b}\right) \le \alpha/2.$$
(21)

$$P(D \le LCL) = P\left(\frac{2D}{b} \le \frac{2LCL}{b}\right) = P\left(\chi_{2a}^2 \le \frac{2LCL}{b}\right) \le \alpha/2.$$
 (22)

However, when the parameters a and b are unknown, their values can be estimated using an observed sample. Under the proposed control chart, the out-of-control probability (P_{out}^0) based on a single sample when the process is incontrol is given by:

$$P_{out}^{0} = P(D \le LCL|a = a_0) + P(D \ge UCL|a = a_0) = P(\chi_{2a_0}^2 \le \frac{2LCL}{b_0}) + P(\chi_{2a_0}^2 \ge \frac{2UCL}{b_0}).$$
 (23)

Hence,

$$ARL_0 = \frac{1}{P_{out}^0} \,. \tag{24}$$

Now, suppose that the shape parameter of the gamma distribution is changed from a_0 to $a_1 = ca_0$ (i.e one or all of the α_i s are changed), for a constant c. By (19), it can be concluded that scale parameter b is shifted to b_1 . Thus, the probability of the process being declared out-of-control based on the single sample when the process is changed is given by:

$$P_{out}^1 = P(D \le LCL | a = a_1) + P(D \ge UCL | a = a_1) = P(\chi_{2\alpha_1}^2 \le \frac{2LCL}{b_1}) + P(\chi_{2\alpha_1}^2 \ge \frac{2UCL}{b_1}). \tag{25}$$

As a result, the out-of-control ARL (ARL_1) for the changing process is obtained as:

$$ARL_1 = \frac{1}{p_{out}^1}. (26)$$

Case2: Normal approximation

According to Wilson & Hilferty (Wilson and Hilferty (1931)), the transformation $D^* = D^{\frac{1}{3}}$ approximately follows a normal distribution with the mean

$$\mu_{D^*} = \frac{b^{\frac{1}{3}} \Gamma(a + \frac{1}{3})}{\Gamma(a)},\tag{27}$$

and variance

$$\sigma_{D^*}^2 = \frac{b^{\frac{2}{3}}\Gamma(a+\frac{2}{3})}{\Gamma(a)} - \mu_{D^*}^2 \ . \tag{28}$$

Having a_0 the shape parameter of the gamma distribution when the process is in control, the traditional Shewhart-type control limits using the above normal approximation can be written as follows:

$$LCL = \mu_{D^*} - k\sigma_{D^*} = \frac{b_0^{\frac{1}{3}}\Gamma(a_0 + \frac{1}{3})}{\Gamma(a_0)} - 3\sqrt{\frac{b_0^{\frac{2}{3}}\Gamma(a_0 + \frac{2}{3})}{\Gamma(a_0)}} - \mu_{D^*}^2,$$
(29)

and

$$UCL = \mu_{D^*} + k\sigma_{D^*} = \frac{b_0^{\frac{1}{3}}\Gamma(a_0 + \frac{1}{3})}{\Gamma(a_0)} + 3\sqrt{\frac{b_0^{\frac{2}{3}}\Gamma(a_0 + \frac{2}{3})}{\Gamma(a_0)} - \mu_{D^*}^2} . \tag{30}$$

In Phase-I monitoring, the unknown parameters a and b are estimated based on the historical data set. Then, under normal approximation, the out-of-control probability when the process is in-control P_{out}^0 is obtained as

$$P_{out}^{0} = P(D^{*} > UCL|a = a_{0}) + P(D^{*} < LCL|a = a_{0}) = 2\Phi(-3).$$
(31)

Thus, the ARL for the in-control process is given by

$$ARL_0 = \frac{1}{P_{out}^0}. (32)$$

In what follows, we assume that the shape parameter of the gamma distribution is changed from a_0 to $a_1 = ca_0$ (i.e one or all of the α_i s are changed) for a constant c. By (19), it can be concluded that the scale parameter b is shifted to b_1 . Then, the probability of the process being declared out-of-control based on the single sample is given by

$$P_{out}^{1} = P(D^{*} > UCL|a = a_{1}) + P(D^{*} < LCL|a = a_{1})$$

$$= \Phi(LCL - \frac{b_{1}^{\frac{1}{3}}\Gamma(a_{1} + \frac{1}{3})}{\Gamma(a_{1})} / (\frac{b_{1}^{\frac{2}{3}}\Gamma(a_{1} + \frac{2}{3})}{\Gamma(a_{1})} - (\frac{b_{1}^{\frac{1}{3}}\Gamma(a_{1} + \frac{1}{3})}{\Gamma(a_{1})})^{2})^{\frac{1}{2}})$$

$$+1 - \Phi(UCL - \frac{b_{1}^{\frac{1}{3}}\Gamma(a_{1} + \frac{1}{3})}{\Gamma(a_{1})} / (\frac{b_{1}^{\frac{2}{3}}\Gamma(a_{1} + \frac{2}{3})}{\Gamma(a_{1})} - (\frac{b_{1}^{\frac{1}{3}}\Gamma(a_{1} + \frac{1}{3})}{\Gamma(a_{1})})^{2})^{\frac{1}{2}}).$$
(33)

Note that, the control limits are calculated when the process is in-control. Besides, the out-of-control ARL for the shifted process is given by:

$$ARL_1 = \frac{1}{P_{out}^1}. (34)$$

5. Efficiency comparison

Comparison among the efficiency of the three control charts proposed in Section 4 is demonstrated in this section. Here, the ARL_1s of the charts are compared for a 3-variable and a 2-variable process when ARL_0s is fixed at 370 for each case. Moreover, $ARL_0 = 200$ is considered when p = 3. The results based on various parameter changes are shown in Tables 3-5.

Table 3. The ARL_1s corresponding to the three proposed control charts when p=3 , $\beta=4$ and $ARL_0=370$.

	$\alpha = (9,7,9) \text{ and } \alpha_0 = 2$				$(5,1,3)$ and $\alpha_0 =$	= 0.5	$\alpha = (4,4,4) \text{ and } \alpha_0 = 2$		
	Normal	Satterwaite	Exact	Normal	Satterwaite	Exact	Normal	Satterwaite	Exact
	Approximation	Approximation	Distribution	Approximation	Approximation	Distribution	Approximation	Approximation	Distribution
c	$\int LCL = 42.14$	$\int LCL = 42.4$	LCL = 44.5	$\int LCL = 7.76$	$\int LCL = 7.96$	$\int LCL = 8.9$	LCL = 8.99	LCL = 9.4	$\int LCL = 11.1$
	UCL = 189.1	UCL = 188.9	UCL = 195.57	UCL = 92.34	UCL = 91.89	UCL = 99.1	UCL = 128.78	UCL = 128.27	UCL = 134.83
0.7	12.3	11.98	10.34	31.53	29.27	27.26	27.56	25.4	19.58
0.8	38.14	37.16	33.38	80.22	75.6	71.65	70.79	66.34	54.66
0.9	141.06	138.77	132.28	202.28	196.34	187.63	185.16	179.15	163.13
1	370.4	370.37	370.1	370.4	370.37	370.2	370.4	370.37	370
1.1	253.27	251.39	283.63	350.57	348.76	407.41	400.71	399.28	416.86
1.2	105.26	103.79	132.89	224.10	219.81	303.63	285.95	280.56	307.67
1.3	45.50	44.78	62.02	132.69	129.14	202.22	182.79	177.71	207.48
1.5	11.25	11.08	15.91	49.24	47.69	86.16	73.71	71.19	93.65
1.7	4.04	4.00	5.39	20.82	20.19	37.88	31.70	30.56	43.71
2.0	1.61	1.62	1.88	7.35	7.16	12.66	10.65	10.32	15.33
2.2	1.21	1.21	1.30	4.28	4.19	6.87	5.86	5.71	8.29
2.5	1.03	1.03	1.05	2.34	2.31	3.33	2.91	2.85	3.84
2.7	1.00	1.00	1.01	1.76	1.74	2.32	2.06	2.03	2.57
3.0	1.00	1.00	1.00	1.32	1.31	1.57	1.44	1.42	1.66
3.2	1.00	1.00	1.00	1.18	1.17	1.33	1.24	1.23	1.36
3.5	1.00	1.00	1.00	1.07	1.06	1.13	1.09	1.08	1.14
3.7	1.00	1.00	1.00	1.03	1.03	1.07	1.04	1.04	1.07

Table 4. The ARL_1s corresponding to the three proposed control charts when p=2 , $\beta=4$ and $ARL_0=370$.

	α = (2,2) and α_0 = 0.5				$(4,4)$ and α_0	= 2	$\alpha = (2,9) \text{ and } \alpha_0 = 0.5$		
	Normal	Satterwaite	Exact	Normal	Satterwaite	Exact	Normal	Satterwaite	Exact
	Approximation $LCL = 1.09$	Approximation $(LCL = 1.28)$	Distribution $LCL = 1.5$	Approximation $LCL = 5.18$	Approximation $LCL = 5.48$	Distribution $LCL = 5.9$	Approximation $(LCL = 13.48)$	Approximation $(LCL = 13.65)$	Distribution $LCL = 13.9$
С	UCL = 56.62	$\{UCL = 56.2$	UCL = 59.59	$\{UCL = 89.81$	UCL = 89.67	UCL = 91.95	${UCL = 97.33}$	UCL = 97.3	$\{UCL = 98.66$
0.7	56.47	48.09	44.64	34.84	31.71	29.3	25.39	24.17	23.68
0.8	120.9	107.91	99.81	85.5	79.53	76.29	69.36	66.52	65.44
0.9	239.17	227.05	212.64	205.13	197.98	196.94	194.12	189.88	186.86
1	370.4	370.37	370	370.4	370.39	370.1	370.4	370.37	370
1.1	396.55	395.61	448.71	383.99	383.05	383.78	290.01	288.02	304.67
1.2	323.5	320.45	399.06	274.8	269.8	285.07	150.37	147.76	163.02
1.3	236.71	231.09	307.95	177.52	172.55	182.85	76. 8	75.13	84.59
1.5	120.81	116.032	167.23	74.08	71.48	80.23	23.88	23.34	26.47
1.7	64.10	61.44	91.47	33.43	32.22	37.42	9.43	9.24	10.35
2.0	27.57	26.43	39.64	12.09	11.7	13.74	3.44	3.40	3.68
2.2	16.86	16.20	23.98	6.91	6.72	7.81	2.18	2.16	2.30
2.5	8.92	8.61	12.3	3.53	3.46	3.91	1.41	1.41	1.46
2.7	6.2	6.01	8.35	2.5	2.46	2.72	1.20	1.20	1.22
3.0	3.9	3.82	5.06	1.71	1.69	1.81	1.06	1.06	1.07
3.2	3.04	2.97	3.82	1.43	1.41	1.50	1.02	1.02	1.03
3.5	2.22	2.18	2.68	1.20	1.19	1.23	1.00	1.00	1.00
3.7	1.88	1.85	2.20	1.11	1.12	1.13	1.00	1.00	1.00

$\alpha = (9,7,9) \text{ and } \alpha_0 = 2$				$\alpha = 0$	$(5,1,3)$ and $\alpha_0 =$	= 0.5	$\alpha = (4,4,4) \text{ and } \alpha_0 = 2$		
	Normal	Satterwaite	Exact	Normal	Satterwaite	Exact	Normal	Satterwaite	Exact
	Approximation	Approximation $LCL = 45.07$	Distribution		Approximation $LCL = 8.92$		Approximation $LCL = 10.36$	Approximation ($LCL = 10.64$	Distribution
c		UCL = 43.07		UCL = 87.52	UCL = 87.08	UCL = 92.82	UCL = 10.30		
L L									
0.7	9.08	8.90	7.38	21.61	20.37	18.5	19.34	18.12	14.09
0.8	25.49	24.99	21.04	50.6	48.27	44.68	45.47	43.16	35.33
0.9	84.23	83.16	73.37	116.8	114.06	107.19	108.06	105.24	94.43
1	200.1	200	200.03	200	200	200.03	200	200	200.03
1.1	141.16	140.33	171.06	189.98	189.45	220.36	213.87	213.60	230.24
1.2	61.91	61.23	83.56	125.15	123.45	166.00	155.26	153.24	174.62
1.3	28.14	27.80	40.04	76.21	74.71	110.93	100.96	98.93	119.3
1.5	7.73	7.65	10.97	38.26	29.19	47.76	42.27	41.25	54.88
1.7	3.09	3.07	4.05	13.4	13.12	21.64	19.1	18.63	26.26
2.0	1.42	1.42	1.61	5.18	5.10	7.8	6.99	6.85	9.73
2.2	1.13	1.13	1.20	3.21	3.17	4.53	4.1	4.032	5.52
2.5	1.02	1.02	1.03	1.91	1.89	2.43	2.24	2.21	2.79
2.7	1.00	1.00	1.00	1.51	1.50	1.80	1.68	1.67	1.99
3.0	1.00	1.00	1.00	1.21	1.20	1.34	1.27	1.27	1.40
3.2	1.00	1.00	1.00	1.11	1.11	1.19	1.14	1.14	1.21
3.5	1.00	1.00	1.00	1.02	1.02	1.07	1.05	1.04	1.07
3.7	1.00	1.00	1.00	1.01	1.01	1.03	1.02	1.02	1.03

Table 5. The ARL₁s corresponding to the three proposed control charts when p = 3, $\beta = 4$ and ARL₀ = 200.

The results in Tables 3-5 show that when c < 1, the control chart based on the exact distribution has smaller ARL_1 values. For example, in the case $ARL_0 = 370$, $\alpha = (9,7,9)$ and c = 0.7 (the first column of Table 3), the value of ARL_1 for the exact distribution is 10.34, while it is 11.98 for the Satterthwaite approximation and 12.3 for the normal approximation. In addition, when c > 1, the control chart based on the Satterthwaite approximation has smaller ARL_1 values; thus it can detect the changes earlier. Besides, based on the results in the above tables one can conclude that for large changes (c > 2.5), the three charts have almost an equal performance in terms of the out-of-control ARL. So, can conclude that the Satterthwaite approximation and the normal approximation are good and appropriate approximations.

6. Conclusions and remarks

In the present article, a multivariate gamma distribution with positive correlations was introduced. Then, by defining a statistic, three control charts were proposed to monitor processes modeled by this distribution. The first control chart was based on the exact distribution of the defined statistic, the second control chart was based on the Satterthwaite approximation, and the third was based on the Wilson-Hilferty approximation. As the Wilson-Hilferty approximation is used to approximate a gamma distribution by a normal distribution, a Shewhart control chart was constructed based on this approximation. The efficiency of these charts was compared in terms of out-of-control ARL, when ARL₀ remains constant. It was observed that whenever the magnitude of the parameter shifts c < 1, the control chart based on the exact distribution had smaller ARL₁s, while for c > 1, the control chart based on Satterthwaite approximation showed smaller values of ARL₁s. Besides, it was observed that for large changes (c > 2.5), all proposed charts had almost equal ARL₁s; i.e. they had the same performance.

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Appendix

Calculating the exact distribution of the *D* statistic

Based on the definition of X_i s, we can write

Based on the definition of
$$X_i$$
 s, we can write
$$D = \sum_{i=1}^p X_i = \sum_{i=1}^p (Y_i + Y_0) = (\sum_{i=1}^p Y_i) + pY_0.$$
 Suppose that $T = \sum_{i=1}^p Y_i$ and $Z = pY_0$. Then, we have

$$T \sim \Gamma(\sum_{i=1}^{p} \alpha_i - p\alpha_0, \beta), Z \sim \Gamma(\alpha_0, p\beta),$$

where T and Z are independent.

Let D=T+Z and W=T. then we have T=W and Z=D-W. Using the change of variables technique, the joint probability density function of D and W is obtained in the following form

$$f_{D,W}(d,w) = f_{Z,T}(d-w,w) = f_Z(d-w)f_T(w)$$

$$= \frac{1}{\Gamma(\alpha_0)\Gamma(\alpha^*)(p\beta)^{\alpha_0}\beta^{\alpha^*}}(d-w)^{\alpha_0-1}e^{-\frac{d-w(1-p)}{p\beta}}w^{\alpha^*-1}, w > 0, \ d > w,$$

where $\alpha^* = (\sum_{i=1}^p \alpha_i) - p\alpha_0$.

By integrating of the above function concerning w and using the change of variable $=\frac{w}{d}$, it can be shown that the probability density function of D is the same as the mentioned probability density function in Equation (3).